



Smart Mobility

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Dr. Om Krishan Singh

Scientist 'D'/Joint Director (R&D in Electronics & IT) Ministry of Electronics and Information Technology Government of India, New Delhi

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Outline of Presentation

- Introduction E-Mobility, Preferences & Statistics
- MeitY- EV initiatives & its Schemes
- Development of Indigenous EV Technology The Journey so far
- Smart Mobility solutions ITS



Introduction







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Limitations of IC Engine

इलेक्ट्रॉनिकी एवं सूचना प्रौद्योगिकी मंत्रालय MINISTRY OF ELECTRONICS AND INFORMATION TECHNOLOGY बने







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Electrification





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Energy Loss: City Driving-



IC Vehicle



Urban Drive Cycle Energy Balance 2005 3 L Toyota Camry

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India Traffic

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Why EVs for INDIA





GoI Target by 2030

To electrify 70% of all CV, 30% of private cars, 40% of buses, and 80% of 2W &3W sales.



EV Market

~ \$206 billion opportunities by 2030 if India maintains steady progress to meet its ambitious 2030 target.



Demand of EV

Rapid increase in registaion of EV



Annual Electric Vehicle sales by category

JMK Research and Analysis

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Programme on Electric Vehicle Sub-system



Deliverable



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Electric Vehicle Components

EV Charger







BMS for EV's Battery

-			
Battery	Advantages	Disadvantages	
NMC	lowest cost,	Slow charging,	
	highest specific	Temperature	
	energy	sensitive	
LTO	Fast Charging),		
	Temperature	Highest cost	
	insensitive,		
LFP	Temperature	Energy-density	
	tolerant	and costs	
	between NMC	between NMC	
	and LTO	and LTO	
	Li-	ion	

Motors for EV

Traditionally used Motor: Induction Motor

- Does not perform efficiently across all speeds; lower efficiency at lower speeds
- Limited Torque delivery

Intermediate Solution : BLDC

- Good for lower power rating
- Uncomfortable drive, and Torque ripple

PMSM Motor

- High efficiency in the entire operating speed range
- High power density, high torque to weight ratio
- Improved driving comfort
- Low cogging torque improves ride experience
- Low torque pulsation

DC-DC
ConverterLi-ion
BatteryDC-DC
ConverterDC-DC
ConverterAuxiliaries

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EV Motors/Controllers



- Technology of Permanent Magnet Synchronous Motor (PMSM)/controller for 2W/ e-Rikshaw has been developed, tested and transferred **to M/s Alphasine and M/s Amber** for production /commercialization.
- Technology of BLDC Motor/controller/vehicle control unit(VCU) is ready and being transferred to **M/s Brushless Motor, M/s Lithion Power** for production





Launching of PMSM Motor



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Indigenous Motor Controller



KEY FEATURES

- 3-half bridge Inverter topology N-Channel Power
- Motor control based on 6-step commutation algorithm with rotor position feedback
- · CAN, UART and Bluetooth communication capabilities
- Test Points to monitor key motor parameters
- Fault Diagnostics capability
- · Compatibility with 5V Throttle



Controller Type	:	Trapezoidal
Input Voltage Range	1	42 - 56V DC
Nominal Voltage	:	48V DC
Nominal Power		1kW
Peak Power	1	2.8kW
Nominal Continuous Current	1	20A
Peak Current	T	60A
Controller Dimensions	1	225×120×75mm(l×b×h)

Contact Us : sales@lithionpower.com | +91 8929065286

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Indigenous Motor Controller



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Digital India Week 2022



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Outcome of EVSS Programme



A **5kW** Sigle Phase AC Charger powered by solar energy



Specification: DC Voltage- 70V-350V AC Voltage- 230V RMS Switching frequency-20kHZ Power-5kW

Line Frequency-50HZ

by solar energy Specification: DC Voltage- 650V 1000V AC Voltage- 230V RMS Switching frequency-20kHZ Power-10kW Line Frequency-50HZ



RATTERY SPECIFICATION

A 10kW Three Phase AC Charger powered

The AI-Enabled Solar-based Multi-port High Gain Electric Vehicle AC Charging Station for domestic and commercial use



Integrated Motherboard



Parameter	Description	Min	Nominal	Max
	Input Specifications			
nput Voltage		450 V	650 V	800 V
nput Current				<7.3 A
nput Capacitance			20 uF	
Efficiency		92%		
Power Consumption @24Vdc				8 W
	Output Specifications			
Dutput Current	(@ 28Vdc)			110 A
Output Power	Continuous 3kW; Peak 3.5kW (for 10 Seconds)			3 kW
Output Voltage Set Point		27.8V	28V	28.06V
Turn-On Delay	From start to Nominal Voltage			60 Sec
Turn-Off Timing	PS WAKEUP delay; (monotonic Vo fall)			100 ms
Output Volt Ripple				2% of Vout
Output Volt Noise				2% of Vout
	Environmental Specifications	5		
	Operating: 62 kPa absolute pressure		3,600	
Operating Temp (Deg C)	Coolant temp with no derating	-40°C	65°C	
	Ambient temp @ full load, with no power derating	-40°C	80°C	

Enclosure size: 200 mm x 160 mm x 75 mm (L x B x H)

3 kW DC-DC converters for medium and small size electric trucks



tery Capacity	20 kWh
I Chemistry	LTC
of Cycles	15000 No:
arging Method	GB/T or 3kw
STEM SPECIFICATIONS	
of AC Outlets	3 No:
of Vehicles Charged Simultaneously	3 Nos @ 3.3 kV
of Fast Charging Ports	1 No:
ximum Output Power	12.5 kV
tput Type	1-phase AC
tput Voltage	230 V
x Output Current	200 A
tem Weight	~560 Kgs
appeippe	215 x 158 x 183 cm

Development and Deployment of EV DC Fast Charger

Development of On-board (In-Vehicle) Fast DC Chargers using High -Speed GaN HeMTs for Two-Wheelers(2W) Electric Vehicles

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OBC Enclosure (Bottom side)



Outcome of EVSS Programme



Parameters		
Operating Conditions		
Voltage	0-96 V	
Operating Temperature Range	-15 to 65 C	
BMS Type	Smart Cloud Storage	
Monitoring	Cloud based real-time monitoring	
User Interface		
Interface	1. Cloud 2. API Integration 3. MQTT based Protocol 4. Bi-directional Communication	
Communication Protocol	1. CAN Bus 2. Wi-Fi	
Security	 GPRS with live monitoring and tracking AWS KMS (Key Management Service) AWS IAM (Identity and Access Management) Authorization and authentication (SQL Database) 	



A Smart Battery Management System with Real-Time Estimation for State of Charge (SoC) and State of Health (SoH) of Electric Vehicles Batteries using Hybrid Models



Design and Development of Next Generation cost-effective Reconfigurable On-Board Battery Charger with Health and Fault Monitoring



DevelopmentofHigh-EfficiencyMotorsandControllers for EVs for IndianDriving Conditions

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Outcome of EVSS Programme





Development of an efficient module-integrated battery management system



Development of highefficiency portable chargers for electric 2W/3W





Performance Parameters: Final Specifications Rated Power 500 watt Peak Power 750 watt **Rated Speed** 264 RPM 350 RPM Peak Speed **Rated Torque** 18.1 Nm **Cogging Torque** 0.859 Nm Stator Teeth Flux Density 1.61 T (No Load) 2.07T (Peak) 3.442 (A/mm^2) Current Density HV testing winding 75 mOhm (Match with Simulation Results) Resistance HV testing winding 0.44 mH (Match with Simulation Results) Inductance Efficiency 87.4 % **IP** Protection IP68 (water + Dust)

Indigenous development and Commercial Possibilities of electronic differential system along with two in-wheel motors for electric 3-wheelers

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National Mission on Power Electronics Technology is a mission programme launched by the Ministry of Electronics and Information Technology (MeitY)

Mission: To facilitate Research, Development, Deployment and Commercialization of Power Electronics Technology by <u>enhancing indigenous R&D</u> <u>expertise and infrastructure</u> in the country with active participation from Academic Institutions and Industries

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NaMPET - Program



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Development of EV Technologies under NaMPET Programme



Development of WBG based EV Supply Equipment for Charging (WBG-EVSE)

Objective and Targets - WBG EVSE

- □ 3.3kW Single Phase AC Charger
- □ 7kW & 22kW AC Fast Chargers
- □ SiC based15kW DC Dual Point
- Charger
- GaN based 3.3kW SPV DC Charger
- □ SiC based 50kW DC fast charger



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Suture-Enhancement



Specification of EV Chargers



Parameter	Values	Parameter	Values	
AC Supply System	Three-Phase 22kW) Single Physe (7kW) AC system	Nominal Input	3-phase 4 KVAC	
Input voltage & frequency	2301, 415V (+10% and -10%) , 51Hz, ±3Hz	Rated Output Power	15 kW/ NokWer (Plygi), 9 3. skwipling 2)	50 kW
Number of outputs	1,00	Switching Frequency	50 kHz	50 kHz
Output Current	32A	Intermediate DC Bus	OO VDC	750 VDC
Output Connector	UEC 60106 Tyme U	Output Voltage	48VDC/72VDC	250 – 420 VDC
Compatibility	TEC 02190 Type II	Output Current	200 A	125 A
EV- EVSE communication	Control pilot and proximity pilot function	Output Connectors	GB/T	CCS CHAdeMO
Parameter	Values	Parameter	Valu	les
AC Supply System	Three-Phose	Nominal Input	230V Single Phase	AC 50Hz
	415V (+10% and -10%) 50Hz	Power	330003	
Input voltage & frequency		SPV Nominal Voltage	205V DC 0	
Number of outputs	aharb	Switching Frequency	100hHz	
Output Current	16 A	Output Voltage	48V DC	
Output Connector	UFC 60309	Intermediate DC Bus of Voltage	400V DC	
Compatibility		Solar Panel Technology	Mono crystalline	
CMS- EVSE communication	OCPP	Output current	68A max.	

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3 Port AC Charger



Single Port AC Charger



22kW AC Fast Charger



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50kW Mechanical Model



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3.3kW SPV DC Charger





- Allows communication between utility and vehicle
- Allow integration of more renewable like wind/solar
- Stationary batteries could be used as stationary batteries for utilities
- Batteries could provide ancillary services







Smart Mobility solutions for Intelligent Transport System -1 Intelligent Transport System Ś Road Safety

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- ATCS Compatible Vehicle Actuated Traffic Signal Controller Adaptive Traffic Control System (ATCS) software capable of handling non-lane based, mixed traffic flow conditions (TraMM-EnV /CoSiCoSt-EnV)
- Pedestrian Safety Enhancement Controller(PeSCo)
- Emergency Service Vehicle Priority System (EmSerV)
- Bus Priority System
- Fleet Management system & Passenger Information System (FMS &PIS)
- Personalized Transit Route Guidance System (PTRGS) for bus passengers



Traffic Signal Controller (Model: CUTE)



Salient Features

- Universal Interface for Vehicle Detector
- Compatible to switch 24V DC lamps
- Green-Green Conflict Monitoring
- Malfunction Management
- Input Voltage Monitoring
- Lamp Intensity control using PWM
- Police Panel Operation (Auto/Manual/Forced flash/ Hurry call)
- Transit Signal Priority for BRTS Bus in dedicated lane
- GPS Based Distributed Time Synchronization
- Remote monitoring of signals through 4G/MLLN link
- Pedestal mount
- Technology readiness –TRL9

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Traffic Signal Monitoring and Management software (TraMM)



TraMM-EnV is a software tool used to remotely monitor and manage a network of Traffic Signal Controllers installed at different traffic junctions in a city from the Traffic Command and Control Centre.

Salient Features

- GIS based user interface with dashboard
- User Management and Alarm Management with SMS, MAIL and Dashboard alerts
- Junction configuration, live animation of traffic signal status and Video Wall display
- Corridor configuration for ATCS
- Time Space Diagram for monitoring signal coordination
- Grouping of junctions for Green corridor
- User defined permanent and temporary scheduler
- Standard and custom reports and charts for data analysis
- Web Service for sharing traffic signal data in Smart City dashboards and other third-party products.
- Technology readiness –TRL9

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CoSiCoSt-EnV is an Adaptive Traffic Control System (ATCS) software algorithm for optimizing signal timings for the typical Indian driving and traffic conditions such as poor lane discipline and high heterogeneity.

Indian Patent (No: 239258) Title: "A Method for Synchronizing Heterogeneous Road Traffic and System thereof"

Salient Features

- Distributed and highly scalable system
- Use Stop-line detection with special filters to address poor lane discipline and high heterogeneity
- Real-time signal coordination in vehicle actuated mode of signal operation.
- Quick offset correction and cycle optimisation
- Plan transition based on Degree of Saturation (DoS)
- Self calibrating
- Green-wave invocation and emergency vehicle prioritising on selected routes
- Prioritising major arterials in a corridor for signal coordination
- Logical isolation and re-join of traffic junctions automatically to manage synchronization in real time
- Technology readiness –TRL9



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• TOT partners – 8 nos.





EmSerV allows the smooth passage of priority enabled Emergency Service Vehicles (ESV) such as ambulances and fire engines through the signalised traffic junctions safely and quickly in emergency situations

Salient Features

- De-centralised solution with GNSS based geo-fencing and RF communication (433MHz & 400m range)
- Central server connectivity with Ethernet
- Include Controller Unit(CU) and Vehicle Mount Unit(VMU)
- Compatible with all traffic signal controller having Hurry Call feature
- Remotely configurable junction parameters
- Vehicle authorization using vehicle IDs
- Gives alert at the junction using hooter on arrival of ESV
- Technology readiness –TRL9





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Technology is ready for TOT, EOI floated **Deploy scenario**

- Controller unit in all traffic junctions in a corridor leading to hospital
- VMU in all emergency service vehicles **Implementation**
- POC implementation in Trivandrum

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Pedestrian Safety Enhancement Controller (PeSCo)



PeSCo is a Pelican Signal Controller which provides extended walk time for differently abled, visually challenged and elderly people by identifying pedestrian demands detected through various input devices detected like push button switch, RFID and ultrasonic sensor devices.

Salient Features

- Provide appropriate Pedestrian Crossing Time based on configuration & category of pedestrian identified
- Programmable Walk time and pedestrian categories
- Provide audio/visual indications for pedestrians wait, stop, and walk
- Instructions in Braille Labels for visually challenged pedestrians
- Pedestrian Detection using Ultrasonic sensors, RFID Card and Push Button
- Audio Instructions for safe crossing
- Technology readiness -TRL9

Industry Connect

- Technology is ready for TOT, EOI floated **Deployment scenario**
- Schools, Hospitals and Midblock pedestrian locations





19.5 inch x 11.6 inch PeSCo Controller Web Interface for PeSCo

Implementation

• POC implementation in Trivandrum

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Bus Priority System at signalized intersections using V2I communication



- Use of DSRC and Wi-Fi devices for TSP application
 - Bus data collection using DSRC
 - Traffic data collection using Wi-Fi sensors
- Intersection traffic state estimation and prediction based on traffic flow theory
- An optimal bus priority system based on predicted traffic state
- Integration and evaluation of the solution with a simulated network
- A scalable and transferable bus priority system for isolated signals



- RSU
 - at intersection
 - Analysis at the control

center

Signal Control



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Vehicle Tracking based Fleet Management System 🋺

(FMS) & Passenger Information System (PIS)



Salient Features

- Intelligent & Automated tracking based fleet management
- Route Management and optimization
- Alerts, Trip Scheduling and Dispatch
- Fleet Utilization and Driver Score Analysis
- Reports & Analytics
- Logistics Tracking
- Vehicle Expense Management
- Decision Support Dashboards
- All in one mobile app based solution
- PIS Mobile App in Android & iOS
- Complaint with AIS-140 standard VLT devices
- Available in cloud and on-premise deployment
- CERT-In certified for security audit
- Technology Readiness -TRL 9

Industry Connect

• TOT – 4nos.

Deployment use case

- Vehicle & Goods Tracking
- Bus Arrival & Personalized Transit Route Guidance Information (Mob App)

Implementation

• Kerala MVD , Civil Supplies Dept, Demo to STA



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Personalized Transit Route Guidance System (PTRGS) for bus passengers



A mobile application for passengers with optimal or customized routes based on real-time information about location of buses and passenger demand. Passengers can find bus stop, bus arrival time, and bus route information and routes can be selected based on minimum **travel time, cost, crowding, or maximum reliability.**

Salient Features

- Real-time transit data using multiple sensors
 - Large amount of data collected through VTU,ETM and Waybill
 - Integrated sensing of transit demand, reliability, traffic and supply characteristics
 - Easy integration with fleet management systems
- Dynamic transit state estimation
 - Data driven and analytical estimation techniques
 - Estimation of travel time, reliability & crowding
- Real-time routing on bus transit network
 - Combines network topology with schedulebased routing
 - Multi-objective and custom routing preferences







Industry Connect

• Software and Hardware are ready for TOT

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India 2024 TOT Partners- Traffic Signal systems & ATCS



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2	M/s. Envoys Electronics Pvt Ltd, Gurgoan
3	M/s. DIMTS Limited, New Delhi
4	M/s. Onnyx Electronysis Pvt Ltd, New Delhi
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6	M/s. Metro Infrasys Pvt Ltd, New Delhi
7	M/s.Electroads, Indore
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9	M/s. Microtrans Infratech Limited, Noida
10	M/s ARS Traffic and Transport Technology (India) Pvt Ltd
11	M/s ITS Planners & Engineers Pvt Ltd, Hyderabad
12	M/s IBI Group
13	M/s L&T

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- 5. M/s. Tak Technologies Pvt. Ltd., Noida
- 6. M/s. Vehant Technologies Pvt. Ltd., Noida
- 7. M/s. Norden Research & Innovation Centre Pvt. Ltd., Kochi
- 8. M/s. Aabmatica Technologies Pvt. Ltd., New Delhi
- 9. M/s. Aditya Infotech Limited, New Delhi

Industrial Vision Sensor - iViS 10GigE

1. M/s. Spookfish Innovations Pvt. Ltd., Bangalore

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Decision Support Tools for Public Transit Agencies FlexiFleet, PTRGS and OSHR

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- 2. M/s. Unidad Techno Labs Pvt. Ltd., Kerala
- 3. M/s. UL Technology Solutions Pvt. Ltd., Kerala
- 4. M/s. Atulya Abhinav Tech Pvt. Ltd., Odisha







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om.krishan@meity.gov.in

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